

(12)

**EUROPEAN PATENT APPLICATION**

(21) Application number: 83103499.6

(51) Int. Cl.<sup>3</sup>: **H 02 K 41/035**  
**H 02 K 41/02, H 01 F 7/16**

(22) Date of filing: 11.04.83

(30) Priority: 12.04.82 US 367361

(43) Date of publication of application:  
19.10.83 Bulletin 83/42

(84) Designated Contracting States:  
AT CH DE FR GB LI NL

(71) Applicant: **POLAROID CORPORATION**  
**549 Technology Square**  
**Cambridge, Massachusetts 02139(US)**

(72) Inventor: **Petersen, Christian C.**  
**206 Conant Road**  
**Westwood, Mass. 02090(US)**

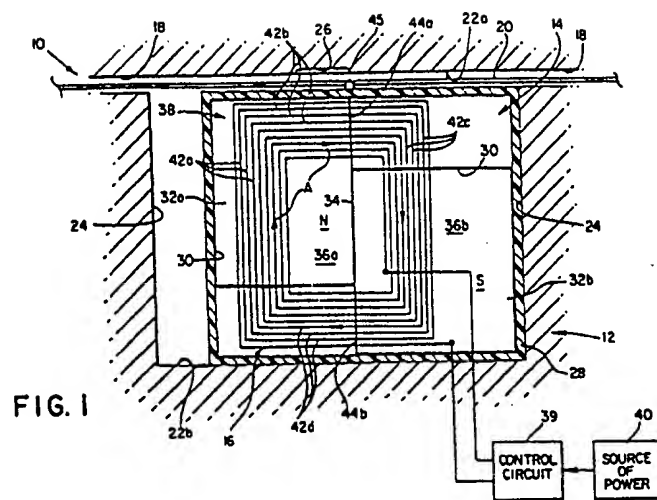
(74) Representative: **Koch, Günther, Dipl.-Ing. et al,**  
**Kaufingerstrasse 8**  
**D-8000 München 2(DE)**

(54) **Electromagnetic actuators.**

(57) An electromagnetic actuator is disclosed comprising a substantially planar, permanent magnet arrangement (32A,B) providing at least one magnetic field extending generally normal to the plane of the magnet arrangement. Included is at least one conductor (38) extending in a conductor plane generally parallel to the plane of the magnet arrangement with a portion of the conductor in intersecting relation to the field, whereby relative motion is effected between the conductor and the magnetic arrangement in their respective planes upon energization of the conductor. In one embodiment the magnetic arrangement is mounted for movement in a multiplicity of directions in the plane of the magnet arrangement and there are a plurality of separately energizeable conductors (80, 82, 84) lying in or close to the conductor plane, each of the conductors having a portion configured for intersecting the one magnetic field at an angle different from other conductors.

**EP 0 091 685 A1**

./...



## Electromagnetic Actuators

### Background of the Invention

This invention relates generally to motion producing apparatus of the electromagnetic kind.

- 5 More particularly, it relates to a method of and apparatus for controlling movement of an armature in an actuator of the electromagnetic kind.

A wide variety of electromagnetic actuators  
10 exists. A typical motor or actuator is of the linear kind and includes a cylindrical bobbin about which is wound one or more field coils. Mounted within the bobbin is an armature. The armature may be comprised of a core formed from a  
15 piece of soft iron, as shown in U. S. Patent No. 3,728,654, or it may be comprised of a plurality of permanent magnets, such as shown in U. S. Patent Nos. 3,022,400, 3,202,886 and 3,495,247, or  
20 the armature may be a combination of a core and a permanent magnet. Through the application of direct current to the coil, a magnetic field is generated for facilitating production of a force sufficient for driving the armature in a given direction. Reverse application of the current

polarity causes the armature to be driven in the opposite direction.

Another kind of linear actuator is disclosed in U.  
5 S. Patent No. 4,265,530. The described actuator returns the armature to an original or central position upon deenergization. While such a linear actuator is successful for the purposes intended, it is limited to producing movement along a linear  
10 path. U. S. Patent No. 3,320,445 discloses a pair of juxtaposed thin flat magnets and a coil with its axis transversely oriented to the plane of the magnets. The coil is energizable for effecting a reciprocating motion of the magnets along a single  
15 fixed axis.

The above linear actuators are effective and small. They can be used in a variety of situations, especially where small space and weight, and low  
20 electric power consumption are desired. Despite their many advantages, however, the actuators suffer from certain limitations. One is that the armatures move along a single path. Hence, the armatures cannot move in multiple directions.

25 U. S. Patent No. 3,836,835 discloses a linear movement positioning system wherein an armature is movable along a single axis or a pair of coordinate axes. U. S. Patent No. 3,904,900 discloses a pulse  
30 operated two-axes magnetic positioning device by which an object can be moved in a first direction, a second direction which is not parallel to the first direction or in any direction between the first and second directions on a horizontal plane.

These devices accomplish the two-axes positioning by a plurality of conventional pulse operated electromagnetic motors.

5 Summary of the Invention

In accordance with the present invention, there is provided an electromagnetic actuator comprising a substantially planar, permanent magnet arrangement  
10 providing at least one magnetic field extending generally normal to the plane of the magnet arrangement. Included in the actuator is at least one conductor extending in a conductor plane generally parallel to the plane of the magnet  
15 arrangement with a portion of the conductor in intersecting relation to the field, whereby relative motion is effected between the conductor and the magnet arrangement in their respective planes upon energization of the conductor.

20 In an illustrated embodiment, the magnet arrangement provides a pair of oppositely polarized fields extending generally normal to the plane of said magnet arrangement and located in  
25 adjacent relation along a given axis of the magnet arrangement and mounted for movement along a multiplicity of directions lying in the plane of the magnet arrangement.

30 In another illustrated embodiment, there are additionally provided separately energizeable conductors lying in or close to the conductor plane, each of the conductors having a portion configured for intersecting the magnetic field at

an angle different from intersecting portions of other conductors.

In another embodiment, there is provided an  
5 actuator wherein the magnet arrangement is an  
elongated member with at least one of the magnetic  
fields being of given minimum width, the given  
axis being the longitudinal axis of said member,  
and the conductor being an elongated loop with a  
10 width greater than the minimum width of said  
magnetic fields and with one of the short portions  
of the loop configured to intersect at least one  
of the magnetic fields to effect the relative  
motion and the long portions of the loop  
15 configured to be generally outside of at least one  
of the magnetic fields.

In accordance with the present invention, there is  
provided a method of generating multidirectional  
20 movement comprising the steps of having a  
permanent magnet arrangement providing at least a  
magnetic field extending generally normal to a  
plane of the magnet arrangement and being mounted  
for movement along a multiplicity of directions  
25 lying in said plane of said magnet arrangement;  
having a plurality of separately energizeable  
conductors lying in or close to said conductor  
plane, each of said conductors having a portion  
thereof configured for intersecting the magnetic  
30 field at an angle different from the other  
conductors; and, energizing selected ones of said  
conductors to effect relative multidirectional  
movement between said magnet arrangement and said  
conductors.

Among the objects of the invention are the provision of an electromagnetic actuator and a method whereby an armature can move in a multiplicity of directions; the provision of an  
5 actuator of the above kind in which an armature can move along a plurality of non-fixed paths by energizing a plurality of energizeable means in a predetermined manner; the provision of an  
10 electromagnetic actuator having a pair of adjacent polar regions of opposite polarity offset with respect to each other along a longitudinal axis and a plurality of conductors physically arranged relative to the offset magnets so as to provide a  
15 plurality of variable driving forces which displace the magnets along variable paths and at variable speeds; the provision of an electromagnetic actuator having a pair of adjacent and oppositely polarized magnetic fields in conjunction with conductors arranged in such a relationship  
20 with respect to the fields so as to eliminate the need for a magnetic flux return member; and the provision of an actuator which has the characteristics mentioned above and which is relatively small in size, constructed of  
25 relatively few components and requires low power consumption for operation.

Other objects and further scope of applicability of the present invention will become apparent from  
30 the detailed description to follow when taken in conjunction with the accompanying drawings, wherein like parts are designated by like reference numerals.

Brief Description of the Drawings

Fig. 1 is a schematic illustrating components of  
the actuator of this invention when in one  
5 position;

Fig. 2 is a schematic similar to Fig. 1, but  
showing the actuator in a different  
position after being actuated;  
10

Fig. 3 is a schematic showing another embodiment  
of an actuator in one position;

Fig. 4 is a schematic similar to Fig. 3, but  
15 showing the actuator in another position  
after being actuated;

Fig. 5 is a schematic planar view showing another  
embodiment of the present invention;  
20

Fig. 6 is a schematic elevational view of the  
actuator shown in Fig. 5;

Fig. 7 is a schematic planar view of another  
25 embodiment of the present invention;

Fig. 8 is a schematic planar view of still  
another embodiment of the present  
invention; and,  
30

Fig. 9 is a schematic planar view of yet another  
embodiment of the present invention.



### Detailed Description

Reference is made to Figs. 1 and 2 showing an actuator 10 made in accordance with the invention.

5 The actuator 10 is supported by and housed in a housing assembly 12. Included in the actuator 10 are magnetic and coil assemblies 14 and 16; respectively. Aligned and spaced apart openings 18 are formed in the housing assembly 12. These  
10 openings 18 permit incremental displacement therethrough of a web of material, such as a continuous drivable belt 20. Formed in the housing assembly 12 are top and bottom interior walls 22a, 22b, respectively, and interior end walls 24. An  
15 elongated guiding slot 26 is formed in the top wall 22a. The interior walls of the housing assembly 12 form means for limiting movement of the magnet arrangement 14.

20 The magnet assembly 14 includes a thin and generally rectangular carrier member 28 made of a non-magnetic and non-conducting material, such as Delrin®. When the carrier 28 is in a stationary normal position (Fig. 1), its bottom surface rests  
25 on bottom wall surface 22b, while the right surface of the carrier abuts the right end wall 24. Formed in the carrier 28 is a pair of generally rectangular recesses 30. Each recess 30 is configured for receiving and retaining therein  
30 one of a pair of thin and generally rectangular permanent magnets 32a, 32b. Although a pair of magnets 32a, 32b is disclosed, the invention contemplates use of a single magnet having a pair of adjacent magnetic domains of opposite polarity.

The magnets 32a, 32b are juxtaposed along a common boundary 34 and are offset vertically relative to each other. This offset allows the formation of electromotive forces for moving the armature or magnet assembly 14 in multiple directions. The pair of magnets 32a, 32b need not lie in the same or parallel planes, but can be angularly oriented with respect to each other. In this embodiment, each of the magnets 32a, 32b is preferably of a rare earth, such as samarium cobalt. The faces 36a, 36b of the permanent magnets 32a, 32b; respectively, define opposite magnetic poles N and S; respectively. The magnetic fields generated by the magnetic faces 36a, 36b extend substantially vertically from the plane of the drawing and interact with the electromagnetic fields created by the stator assembly 16 for driving the armature assembly 14. Since the magnets 32a and 32b are rare earth magnets, their fields tend to be ballistic. In other words, they extend upwardly from the faces in an area which is coextensive with the area of the faces.

The coil assembly 16 includes a continuous, generally planar and rectangular electrical conducting field coil 38. The coil 38 has a plurality of windings connected to a suitable control circuit 39 and source of preferably DC power 40. The control circuit 39 controls the amplitude and polarity of the electric current passing through the coil 38. The field coil 38 can be housed in a plastic jacket (not shown). The field coil 38 is stationary, and is fixedly connected to the housing assembly 12 by

conventional means (not shown). The magnet assembly 14 moves at a speed and in a direction which depend on the magnitude and on the direction, respectively, of the current flowing in the coil 38.

The windings of the field coil 38 are divisible into four interconnected coil segments 42a-d. Each segment is generally transversely oriented to the adjacent coil segments. Because of this arrangement the coil segment 42a has current flowing through it in a direction opposite to the current in the coil segment 42c; while the coil segment 42b has current flowing through it in a direction opposite to the current flow in the coil segment 42d.

The coil segments 42a, 42c extend across respective portions of the magnetic faces 36a, 36b. Transversely disposed coil segments 42b and 42d extend across offset and extending portions 44a, 44b of the magnets 32a, 32b; respectively. Thus, the transversely disposed coil segments 42a, 42b extend across and into the magnetic field of the permanent magnet 32a, while the coil segments 42c, 42d extend across and into the magnetic field of the permanent magnet 32b.

The innermost windings of the coil segments 42a, 42c are spaced from the common boundary 34.

Each of the groups of coil segments 42a, 42c has a combined width along the horizontal axis, which is significantly less than the length of the magnetic

fields defined by the faces 36a, 36b along the same axis, and the innermost windings are sufficiently spaced from the boundary 34 that during horizontal translation of the assembly 14, 5 the coil segments 42a, 42c do not intercept the adjacent magnetic field. Because of this relationship, there is no need to have a flux return plate spaced above the coil 38 to insure that the flux of the magnetic north pole travels 10 upwardly through the coil segments 42a, 42b and to the magnetic south pole back through the other coil segments 42c, 42d. Without a flux return plate the actuator can be made much thinner and lighter than has been possible before. Also, the 15 innermost windings of the top and bottom coil segments 42b, 42d are spaced from the top and bottom ends of the magnets 32b, 32a; respectively. These spacings are sufficient to insure that when the magnet assembly 14 is vertically translated 20 the magnet face 36b will not intercept the coil segments 42b and the magnetic face 36a will not intercept the coil segments 44b.

The operation of this embodiment will now be 25 described. For purposes of driving the belt 20 to the left (Fig. 1), electrical current is supplied to the field coil 38. The direction of the current is indicated by the arrows A; and, as a result, the magnet assembly 14 moves to the position shown 30 in Fig. 2. The magnet assembly 14 is, in effect, driven simultaneously both upwardly and leftwardly from the position shown in Fig. 1. The leftward translational component of the movement is generated by the interaction of the electromagnetic

fields of the opposing coil segments 42a, 42c with the magnetic fields of the permanent magnets 32a, 32b; respectively. More specifically, the energized coil segments 42a create electromagnetic fields which interact with the north magnetic field of the permanent magnet 32 to drive the magnet assembly 14 to the left. At the same time a leftward driving force is produced as a result of the interaction of the electromagnetic fields of the coil segments 42c with the south magnetic field of the magnet 32b. The upward driving force component is created because of the interaction of the electromagnetic fields of the opposing coil segments 34b, 34d interacting exclusively and respectively with the opposing magnetic fields of the offset magnetic portions 44a, 44b. During upward movement, a projection 45 on the carrier 28 enters a sprocket hole (not shown) of the belt 20 and engages and then slides within the guide slot 26. The guide slot 26 guides the carrier 28 leftwardly, and the belt 20 is thus driven. Obviously, the inner walls of the housing assembly 12 limit movement of the magnet assembly 14.

For returning the magnet assembly 14 to the position in Fig. 1, the control circuit 39 is operated to reverse the polarity of the current flowing through the field coil 38. This reverses the direction of the electromagnetic fields produced by the coil segments 42a-d. The reversed fields interact with the magnetic fields of the magnets 32a, 32b in a manner to drive the magnet assembly 14 to the right and downwardly. This reverse movement continues until the magnet

assembly 14 comes to rest against the bottom and right inner walls of the housing assembly 12. (Fig. 1). During this return, the driving projection 45 releases the belt 20. It will be appreciated that  
5 the belt 20 has been incrementally advanced leftwardly by a preselected distance.

The foregoing describes the sequence of events during an operational cycle. Obviously, by  
10 repeating such cycle, the belt 20 is continuously incrementally driven.

Reference is now made to Figs. 3 and 4 for describing an alternate embodiment. The structure  
15 of this embodiment which is similar to the previous embodiment is indicated by like reference numerals primed. In this embodiment the magnet assembly 14' is not fixed and is allowed to move in multiple directions to advance the belt  
20 20' incrementally.

The movable magnet assembly 14' includes a second generally thin and rectangular carrier 46. The carrier 46 is configured to retain for movement  
25 therein the carrier 28' and is constructed of the same material as the carrier 28'. The carrier 28' is vertically movable within a space defined by the carrier 46. The carrier 46 is also longitudinally slidable between the end walls 24'  
30 while being in sliding engagement with the top and bottom wall surfaces 22'. Opposite end walls of the carrier 46 have openings 48 aligned with the openings 18' for allowing passage therethrough of the belt 20'.

The conducting coil 38' is juxtaposed to the planar magnets 32'a, 32'b so that the coil segments 42'a, 42'b remain within the magnetic field of the permanent magnet 32'a, while the coil  
5 segments 42'c, 42'd remain within the magnetic field of the permanent magnet 32'b during movement of the armature assembly 14'.

In the operation of this embodiment, the field  
10 coil 38' is energized by the control circuit. Assuming the current to flow in the direction of the arrows shown in Fig. 3, the carrier 28' is moved upwardly relative to the carrier 46 until the projection 45' projects through a sprocket  
15 hole in the belt 20' and engages an opening in the carrier 46. This forces the belt 20' into tight frictional engagement with the interior of the carrier 46. Simultaneously, the carrier 46 is driven to the left by the magnet assembly 14'  
20 until it engages the left end wall 24' (Fig. 4). Consequently, the belt 20' is driven leftwardly. Moreover, because the belt 20' is sandwiched between the carriers 28' and 46, it is not touch  
25 This reduces significantly friction on the belt 20' and thereby enhances its useful life.

Of course, reversing the polarity of the current through the field coil 38' causes the carriers  
30 28', 46 to return to their normal positions (Fig. 3). By repeating this cycle, the belt 20' is incrementally driven.

Reference is now made to Figs. 5 and 6 which show

another embodiment of this invention. It differs from the others in that the magnet assembly 50 reciprocates along a single axis 51. In this embodiment a magnet assembly 50 comprises a pair  
5 of thin permanent, preferably rare earth, magnets 52a, 52b, such as samarium cobalt. Although a pair of magnets is disclosed, a single magnet could be used, but with a pair of polar regions on a single surface thereof. The magnets 52a, 52b are coupled  
10 together along a common boundary 54 and move in unison with each other. The magnets 52a, 52b may be spaced from each other. The magnet 52a may have its top surface with a south magnetic pole S, while its bottom surface would have a north  
15 magnetic pole N. On the other hand, magnet 52b has a north magnetic pole N on the top and a south magnetic pole S on the bottom. The magnets 52a, 52b are mounted in recesses of a plastic carrier 56. The magnet assembly 50 is movable relative to  
20 a pair of spaced apart and identical top and bottom planar coils 58, 60; respectively.

The coils 58, 60 are respectively superposed relative to the top and bottom surfaces of the  
25 permanent magnets 52a, 52b. The coil 60 is not seen in Fig. 6 because it is below the coil 58. The coils 58 and 60 may be mounted in plastic material and stationarily affixed. The segments 58a, 60a; and 58c, 60c, respectively, remain  
30 within the magnetic fields of their magnets 52a, 52b.

As seen best in Fig. 5, the current in coil segment 58a is opposed in direction to that in



58c, while the current in the coil segment 60a flows in a direction opposite to that in coil segment 60c. While the coil segments 58b, 58d; 60b, 60d (not shown but corresponding to the coil segments 58b, 58d) are energized, they do not interact with the noted magnetic fields because they are positioned outside the magnetic fields. Because the permanent magnets are of the rare earth type, their fields have a ballistic effect; that is, their fields extend from the magnet faces so that they tend to be concentrated in the area defined by the magnetic faces. Thus, only the coil segments 58a, 58c and 60a, 60c contribute to the translatory motion. As noted previously, the combined width dimensions of each of the bundle of coil segments 58a, 58c; 60a, 60c along the longitudinal axis 51 are less than the dimensions of the respective magnetic fields they are in. The axial translation of the magnet assembly 50 is such that the coil segments 58a, 58c; 60a, 60c will not cross the boundary 54 and thus will remain outside the field of the adjacent magnetic field. For instance, flux from the north pole of magnet 52b will travel upwardly through the coil segments 58c and downwardly through the coil segments 58a to the south pole of the magnet 52a. Thus, the possibility of flux traversing the same coil segments twice is eliminated. Although not necessary, a pair of spaced apart flux return plates (not shown) can be provided. Each plate would be superposed above a respective one of the conducting coils 58, 60.

Operation of this embodiment is as follows.

Through operation of a control circuit preferably DC current flows from a power source (not shown) through the top conducting coil 58 in the direction of the arrows in Fig. 6. This creates opposing  
5 electromagnetic fields in the coil segments 58a, 58c. These opposing fields interact with respective ones of the opposing magnetic fields of the magnets 52a, 52b to drive the magnet assembly 50 linearly to the right. Thus, one of the output  
10 members 66 connected to the carrier 56 moves rightwardly. Such movement is stopped when the carrier 56 abuts against a motion limiting stop indicated schematically by reference numeral 70. To drive the magnet assembly 50 in the reverse  
15 direction, the lower conducting coil 60 is energized by the control circuit, while the top conducting coil 58 is deenergized. Further, towards that end the current will flow in the coil 60 in a direction opposite that of the coil 58. In  
20 this regard, the coil segments 60a have the current flowing out of the plane of the drawings and the segments 60c have the current flowing into the plane of the drawing. The coil segments 60a, 60c create electromagnetic fields with opposing  
25 directions that interact with the opposite magnetic fields of the magnets 52a, 52b. As a result, the magnet assembly 50 is driven in the reverse direction (i. e., leftwardly) until the carrier 56 abuts against the other motion limiting  
30 stop 70. Accordingly, by having a control circuit alternate the energization of the top and bottom coils 58, 60 in the manner indicated the magnet assembly 50 can easily reciprocate.

Although this embodiment describes that the magnetic assembly 50 is movable, it should be understood that it can be stationary and the coils 58 and 60 made movable. Also, although this  
5 embodiment discloses a pair of coils 58 and 60 for effecting bidirectional translation a single coil can be used instead. By reversing the polarity of current through a single coil, bidirectional movement of the magnet assembly 50 can be  
10 achieved.

Fig. 7 shows another embodiment of the invention. The magnet assembly 76 can be controlled to move along transverse axes and along any axis between  
15 the transverse axes. The magnet assembly 76 includes a carrier member 78 which has recesses formed therein for receiving and maintaining in juxtaposed offset relationship a pair of permanent magnets 78a, 78b. The carrier 78 can be made of a  
20 suitable non-magnetic and non-conducting material, as Delrin<sup>®</sup>. The magnets have opposing magnetic polar regions facing in a common direction (i. e., from the plane of the drawing). In this embodiment, the magnet 78a has its north pole N region facing  
25 upwardly while the magnet 78b has its south pole S region facing upwardly. These permanent magnets are preferably of the rare earth type, such as samarium cobalt. To effect the desired movement there is provided a plurality of superposed planar  
30 coils 80, 82 and 84. Each of the flat coil segments 80, 82 and 84 are directly connected to a control circuit 86. The control circuit 86 can be of any conventional type and serves to digitally control, preferably DC, voltages from the source

of power 87 to the various coils 80-84 in certain predetermined sequences so that the polarity and amplitude of the voltage regulates the direction and speed of the armature assembly 76. Each of the  
5 coils 80-84 may be encased in a plastic jacket (not shown) and stationarily affixed relative to the movable magnet assembly 76 shown in Fig. 7.

The coil assembly 80 has horizontal segments 80a  
10 traversing across the north polar field of the permanent magnet 78a. Since the other coil segments of the coil 80 are outside the magnetic field of the magnet 78a the current flowing  
15 magnet assembly 76 insofar as there is an absence of interaction between their electromagnetic fields and the field of the permanent magnet 78a. When current flows through the coil 80 in the direction indicated, it will cause an upward force  
20 on the magnet assembly 76.

The coil assembly 82 is effective for longitudinally translating the magnet assembly 76 along the horizontal axis. When the current flows  
25 in the direction of the arrows (Fig. 7), the vertically extending coil segments 82a and 82c are effective to cause longitudinal movement to the right. The current flowing in the coil segments 82a, and 82c is in opposite directions. Since each  
30 of the electromagnetic fields generated by these coil segments is in the opposite directions, they respectively cooperate with the magnetic fields of the permanent magnets 78a, 78b to effect a rightward displacement. To effect a leftward

displacement, current can be passed through the flat coil 82 in the opposite direction from the control circuit 86. In this particular embodiment, the coil segments 82b and 82d do not effect  
5 movement because they, in effect, cancel each other out. Stated somewhat differently, the force generated by the permanent magnets 78a and 78b with the coil segment 82b is such that it is equal to and offsets the forces generated by the coiled  
10 segments 82d and the permanent magnets 78a and 78b. To insure that these forces cancel each other out, it will be appreciated that their lengths and number of windings or elements in each segment are equal.

15 To effect downward vertical movement, the coil assembly 84 is energized by the control circuit 86. If the current flows in the direction of the arrow indicated in Fig. 7, the coil segments 84a  
20 are effective to interact with the south pole S of the magnet 78b so as to effect a downward vertical displacement of the magnet assembly 76. The other segments of the coil 84 do not interfere with the magnetic field of the south pole.

25 Although this embodiment has been described with three planar coils, it will be appreciated that the noted movement can be affected by two planar coils, such as the planar coil 80 and 82. In this  
30 latter case, current would selectively flow through the coil 80 in opposing directions to effectuate vertical reciprocation.

It is believed the operation of the foregoing

described embodiment has been evident from the description above. However, to supplement the foregoing the following brief description will be set forth. To advance the armature assembly 78  
5 only rightwardly from the position shown in Fig. 7, current is sent through the coil 82 as indicated by the arrows. The opposing coil segments 82a and 82c cooperate with their respective magnetic fields to act in unison for  
10 driving the armature assembly 76 rightwardly. Upward vertical movement is imparted to the armature assembly 76 by energizing the top planar coil 80. Towards this end, the coil segments 80a have current flowing therethrough to establish an  
15 electromagnetic field which cooperates with the magnetic field of the permanent magnet 78a to bring about upward vertical movement. Downward movement can be effected by energizing the coil 84. If the coils 80, 82 and 84 are simultaneously  
20 energized the armature assembly 76 will move with the force and in a direction which is the resultant of the forces created by these coils. Thus, it is possible to move the armature assembly 76 not only along the vertical or horizontal axes,  
25 but along any desired axes in between. This would be determined by the magnitude and direction of current flow in the coils 80-84. By reversing the polarity and by varying current amplitude, the direction and speed of movement of the armature  
30 assembly 76 can be changed as desired. Thus a highly compact and effective actuator is provided which allows not only an armature to move in multiple directions but in a manner which can be easily and precisely controlled.

Reference is now made to Fig. 8 for purposes of showing another embodiment of the present invention. This embodiment is similar to the one described in Fig. 7. This actuator 90 includes a  
5 movable armature or magnet assembly 92 having a plastic jacket 94 with rectangular recesses formed in and offset with respect to each other for receiving and maintaining in offset fashion a pair of permanent magnets 96a and 96b. These magnets  
10 96a, 96b are, preferably, of the rare earth type, such as samarium cobalt. The magnet 94a has its north polar face N facing outwardly, while the magnet 94b has its south polar face S facing outwardly from the plane of the paper. Superposed  
15 at right angles to each other is a pair of stationary flat rectangular coils 98 and 100. Each of the coils 98 and 100 is connected to a suitable control circuit 102 which can control DC current to the coils 98, 100.

20 In this embodiment, coil segments 98a extend across the north magnetic field of the permanent magnet 96a, whereas the coil segments 98c extend across the south magnetic field of the permanent  
25 magnet 96b. The field coil 100 has the coil segments 100a extend horizontally through the south magnetic field of the magnet 96b, whereas the segments 100c extend horizontally through the north magnetic field of permanent magnet 96a. It  
30 will be noted that the end coil segments of each of the field coils 98 and 100 extend beyond the permanent magnets 96a and 96b. Therefore, it is intended that these end portions not interact with the noted magnetic fields. In this manner, they,

when energized, do not alter the desired movement of the magnet assembly.

5 An area 104 is defined by the overlapping transverse coils 98 and 100 which has no overlapping of the coil segments. This area 104 defines the preferred metes and bounds in which the central point 106 can be moved to by taking any number of paths. These paths are controlled  
10 by the control circuit 102 controlling the voltage transmitted to the field coils 98, 100. More specifically, the amplitude and polarity of the current in the coils 98, 100 can be regulated, whereby the speed and direction of movement of the  
15 central point 106 within the central area 104 is regulated so as to move to the central point 106 from one point to another along any desired path.

20 In operation, the magnet assembly 92 can move upwardly vertically, if current is travelling through the coil 100 in the direction indicated by the arrows in Fig. 8. Thus, the coil segments 100a interact with the south pole S and the coil  
25 segments 100c interact with the north pole N to drive the magnet assembly 92 including the central point 106 upwardly. Thus, both of these forces act in conjunction with each other. It will be appreciated that to drive the magnet assembly  
30 vertically downwardly the control circuit 102 merely has to change the polarity of the voltage transmitted to the coil 100. To affect horizontal movement of the magnet assembly 92, it will be appreciated that the control circuit 102 can



transmit voltages to the field coil 98 in a manner such that the coil segments 98a interact with the north magnetic field generated by magnet 96a and the coil segments 98c interact with the south magnetic pole of the magnet 96b. If the flow of current is in the direction of the arrows, this movement is a rightward linear displacement of the magnet assembly 92. It will be appreciated that to effect only rightward movement, the field coil 100 is deenergized. On the other hand, to move the central point 106 in any given direction within the central area 104, it is possible to have the control circuit 102 to vary voltages transmitted to the field coils 98 and 100 such that their polarity and amplitude can vary the direction and speed at which the magnet assembly 92 can move. Thus, the central point 106 can move at a speed and in a direction which depends upon the proportion of the magnitude and direction of current flowing in the field coils 98 and 100.

As with the previous embodiment, although the present invention has described that the magnet assembly 92 is movable relative to the coils 98, 100, it will be appreciated that these coils can be made movable relative to a fixed magnet assembly.

Although movement of the armature assembly 92 has been described above wherein the point 106 can preferably move within the central area 104, the actuator 90 would still function, but in a less precise and efficient manner if the central point 106 traveled beyond this area. This would be so

because it would mean that the magnets 96a, 96b would interfere with other coil segments of the coils 98, 100 which would produce countervailing forces to the desired driving forces.

5

Reference is now made to Fig. 9 showing another embodiment of the present invention. In this embodiment, a permanent magnet 110 has its face 112 defining a north magnetic pole N. Preferably, 10 the magnet 110 is of the rare earth type and is mounted by means not shown for multidirectional movement in the plane of the drawing.

Disposed in juxtaposed relationship above the 15 magnet face 112 is a plurality of field coils 114, 116, 118. The coils 114-118 are at different angular orientations with respect to each other and the magnet 110. Although the coils 114-118 are shown in the same plane, they need not be. These 20 coils 114-118 are similar to those of the previous embodiment and are mounted so as to be stationary. A control circuit (not shown, but similar to those described above) is connected to each of the coils 114-118 and can control the amplitude and polarity 25 of the DC voltage passing to separate ones of them. The control circuit can selectively energize the coils 114-118 so as to effect relative movement between the magnet 110 and the coils 114-118 in a manner to be described. Referring 30 back to the coils 114-118, they have their respective segments 114a-118a over a portion of the magnet face 112. Separate energization of respective ones of the field coils would cause movement of the magnet 110 transversely to the

respective ones of the coil segments 114a-118a as indicated by the force vector lines  $F_v$ .

To effect movement of the magnet 110 along a given  
5 path and in a given direction relative to the  
field coils 114-118, voltage is supplied to  
selected ones of the coils by the control circuit.  
By selecting which of the coils are to be  
energized as well as the magnitude and polarity of  
10 the voltages supplied thereto, movement of the  
magnet 110 can be controlled. For instance, if  
only the coils 114 and 116 are energized with  
voltages having the same magnitude and polarity as  
indicated by the arrows in the segments 114a,  
15 116a, the magnet 110 will move in a path,  
generally coincident with the force vector  $F_v$  of  
the coil 118, and with a magnitude which is the  
resultant of the force vectors  $F_v$  of the segments  
114a, 116a. Although magnet movement has been  
20 illustrated along such a path, it will be  
appreciated readily that by varying the polarity  
and magnitude of the voltage to selected ones or  
all of the field coils 114-118 movement of the  
magnet 110 can be controlled along multiple  
25 directions.

Moreover, it should be noted that although this  
embodiment shows three field coils and a magnet,  
other numbers of field coils and magnets can be  
30 used consistent with the teachings of this  
invention.

The actuators described above need not be  
restricted to a single moving element. They may

contain multiple individually controllable  
elements. They may also obtain positional control  
via a digital step-by-step technique or via a  
single linear proportional control. The actuators  
5 are not restricted to open or closed loop  
control.

Since certain changes may be made in the above-  
described apparatus without departing from the  
10 scope of the invention herein involved, it is  
intended that all matter contained in the  
description or shown in the accompanying drawings  
shall be interpreted as illustrative and not in a  
limiting sense.

Claims:

1. An electromagnetic actuator comprising:
  - a permanent magnet arrangement having at least one magnetic field extending therefrom;
  - 5    - at least one extended conductor; and
  - means for mounting said magnet arrangement and said conductor in overlying planes with said one magnetic field at an angle to said planes and with at least a portion of said conductor in intersecting relation to said magnetic field so as to effect relative motion between said magnet arrangement and said conductor upon energization of said conductor, and said mounting means including means for fixedly mounting one of said magnet arrangement and said conductor in its plane and for mounting the other thereof for translational movement in a plurality of directions in its plane whereby said other of said magnet arrangement and said conductor is displaced in one of said plurality of directions in its said plane in accordance with said energization.
  - 10
  - 15
  - 20
- 25    2. The actuator of claim 1 wherein said magnet arrangement is a substantially planar arrangement providing said one field generally normal to the plane of said magnet and said overlying planes are generally parallel to said planar arrangement.
- 30
3. The actuator of claim 1 wherein said magnet

arrangement provides a pair of oppositely polarized fields extending generally normal to the plane of said magnet arrangement and located in adjacent relation along a given axis of said magnet arrangement.

- 5
4. The actuator of claim 1 wherein said conductor includes portions angled with respect to each other whereby said other of said magnet arrangement and said conductor is displaced in a preferred one of said directions upon energization of said conductor.
- 10
5. The actuator of claim 1 having a plurality of separately energizeable conductors lying in or close to said conductor plane, each of said conductors having a portion thereto configured for intersecting said magnetic field at an angle different from intersecting portions of other conductors.
- 15
- 20
6. A thin electromagnetic actuator comprising:
- a substantially planar, permanent magnet arrangement of relatively thin cross section providing at least one magnetic field extending generally normal to the plane of said magnet arrangement;
  - at least one extended conductor; and
  - means for mounting said magnet arrangement and conductor in overlying planes generally parallel to said plane of said magnet arrangement with a portion of said conductor in intersecting relation to said magnetic field whereby relative motion is provided
- 25
- 30

between said conductor and said magnet  
arrangement in their respective planes upon  
energization of said conductor, and said  
mounting means including means for fixedly  
5 mounting one of said magnet arrangement and  
said conductor in its plane and for mounting  
the other thereof for translational movement  
in a plurality of directions in its plane  
whereby said other of said magnet arrangement  
10 and conductor is displaced in one of said  
plurality of directions in its said plane in  
accordance with said energization.

7. The actuator of claim 6 wherein said permanent  
15 magnet arrangement provides a pair of  
oppositely polarized fields extending  
generally normal to the plane of said magnet  
arrangement and located in adjacent relation  
along a given axis of said magnet arrangement.

20 8. The actuator of claim 7 wherein said magnet  
arrangement is an elongated arrangement as  
measured along said given axis with at least  
one of said fields being of given minimum  
25 width, said given axis being the longitudinal  
axis of said member, and said conductor being  
an elongated loop with a width slightly  
greater than said given minimum width of said  
magnetic fields and with one of the short  
30 portions of said loop configured to intersect  
at least one of said magnetic fields to effect  
said relative motion.

9. The actuator of claim 8 wherein said magnet

arrangement produces said adjacent magnetic fields at least slightly offset on opposite sides of said longitudinal axis, and said width of said loop while being greater than  
5 said given minimum width is equal to or less than said given width plus the amount of offset when said longitudinal axis of said magnet arrangement is aligned with the longitudinal axis of said loop so that said  
10 long portions of said loop lie in an offset portion of said fields whereby relative motion between said magnet arrangement and said conductor is both along said given axis and normal thereto upon energization of said  
15 conductor loop.

10. The actuator of claim 8 wherein said magnet arrangement produces said adjacent magnetic fields at least slightly offset along a  
20 transverse axis of said magnetic arrangement on opposite sides of said longitudinal axis and said conductor loop is of a width such that when said longitudinal axis of said elongated arrangement is aligned with the  
25 longitudinal axis of said loop the long portions of said loop lie in one of the offset portions of one of said magnetic fields respectively whereby relative motion is produced along both said longitudinal axis and  
30 the transverse axis of said magnet arrangement.

11. The actuator of claim 10 including a plurality of elongated conductor loops mounted in planes



generally parallel to said plane of said magnet arrangement with the longitudinal axis of each conductor loop being rotated in the plane of its respective loop with respect to another loop such that energization of any given loop tends to produce relative motion along the longitudinal axis of that loop whereby both translational and rotational relative movement are achieved by successive energization of different loops.

12. The actuator of claim 11 wherein said magnet arrangement produces said adjacent magnetic fields at least slightly offset along a transverse axis of said magnetic arrangement on opposite sides of said longitudinal axis and said conductor loop is of a width such that when said longitudinal axis of said elongated arrangement is aligned with the longitudinal axis of said loop the long portions of said loop lie in one of the offset portions of one of said magnetic fields respectively whereby relative motion is produced along both said longitudinal axis and the transverse axis of said magnet arrangement.

13. An electromagnetic actuator comprising:  
- a permanent magnet arrangement providing a pair of oppositely polarized fields extending in angularly offset directions from said magnet arrangement;  
- a conductor assembly having a first conductor portion and a second conductor portion; and

- means for mounting said magnet arrangement  
and said conductor assembly for relative  
movement with respect to each other and with  
said first conductor portion extending in a  
5 first conductor plane generally normal to  
one of said fields and said second conductor  
portion extending in a second conductor  
plane generally normal to the other of said  
fields, said mounting means including means  
10 for fixedly mounting one of said magnet  
arrangement and said conductor assembly and  
for mounting the other thereof for  
translational movement in a plurality of  
directions in planes at least parallel to  
15 said first and second conductor planes  
whereby said other of said magnet  
arrangement and said conductor assembly is  
displaced in one direction in each of its  
planes upon energization of said conductor  
20 assembly.

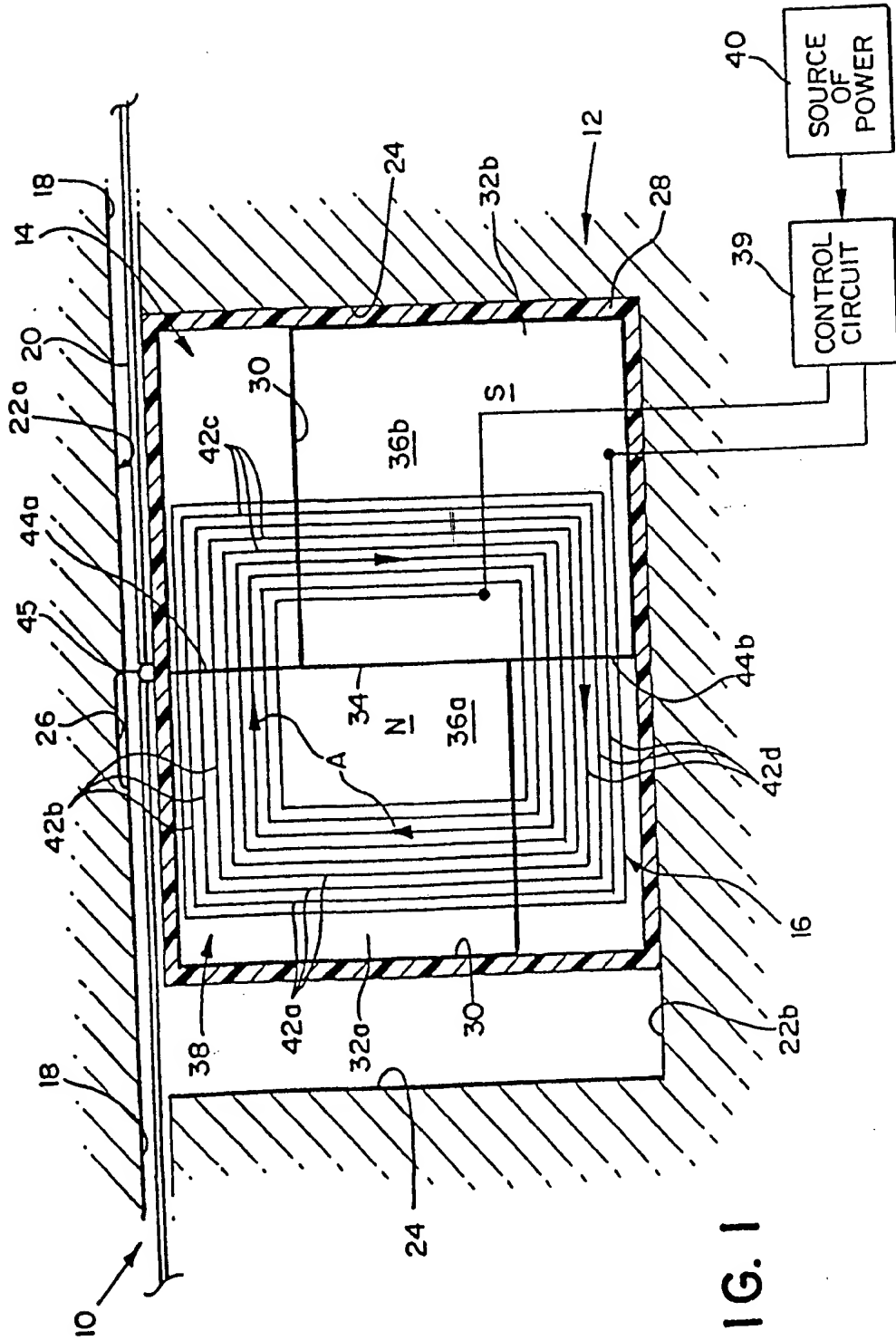
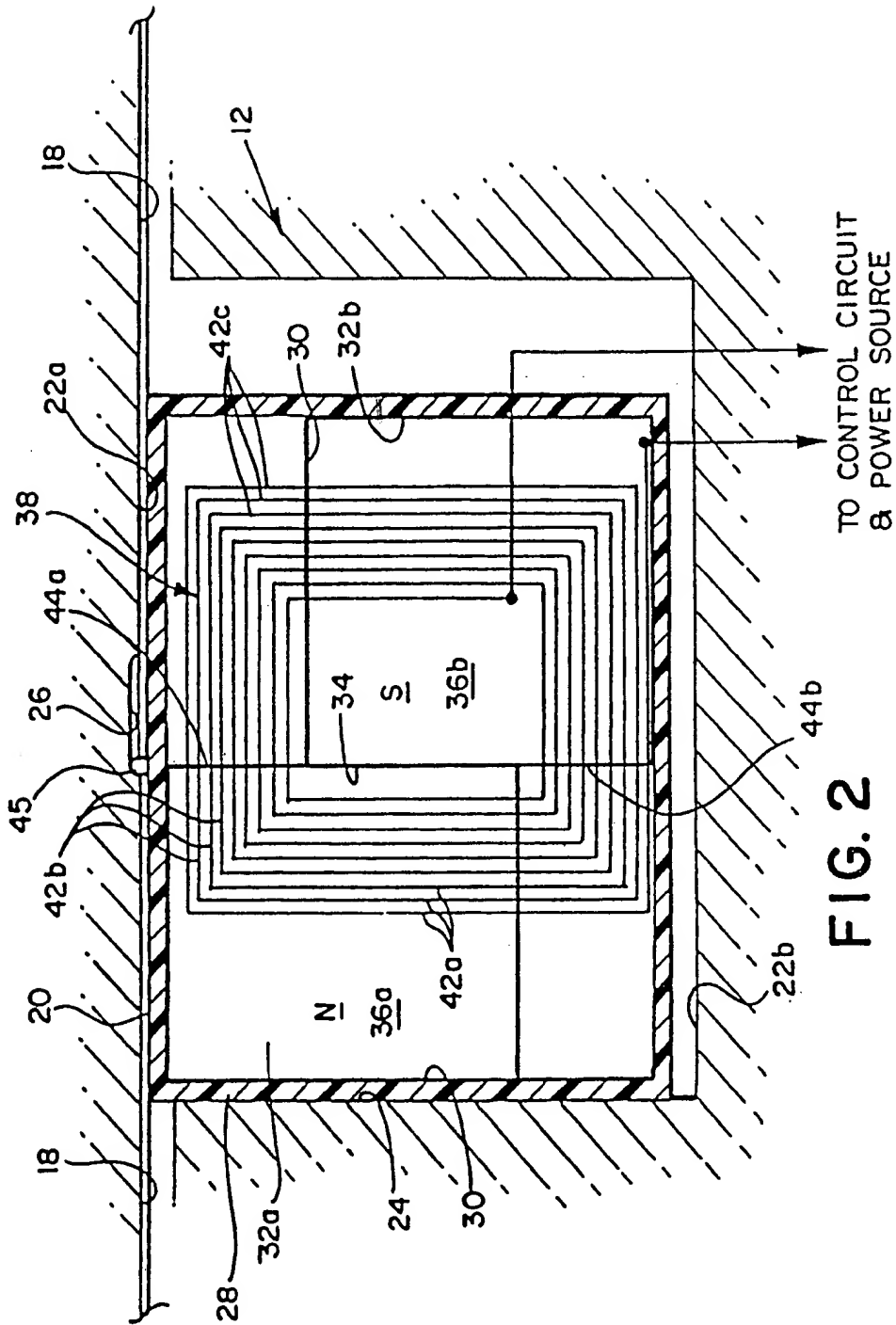


FIG. 1



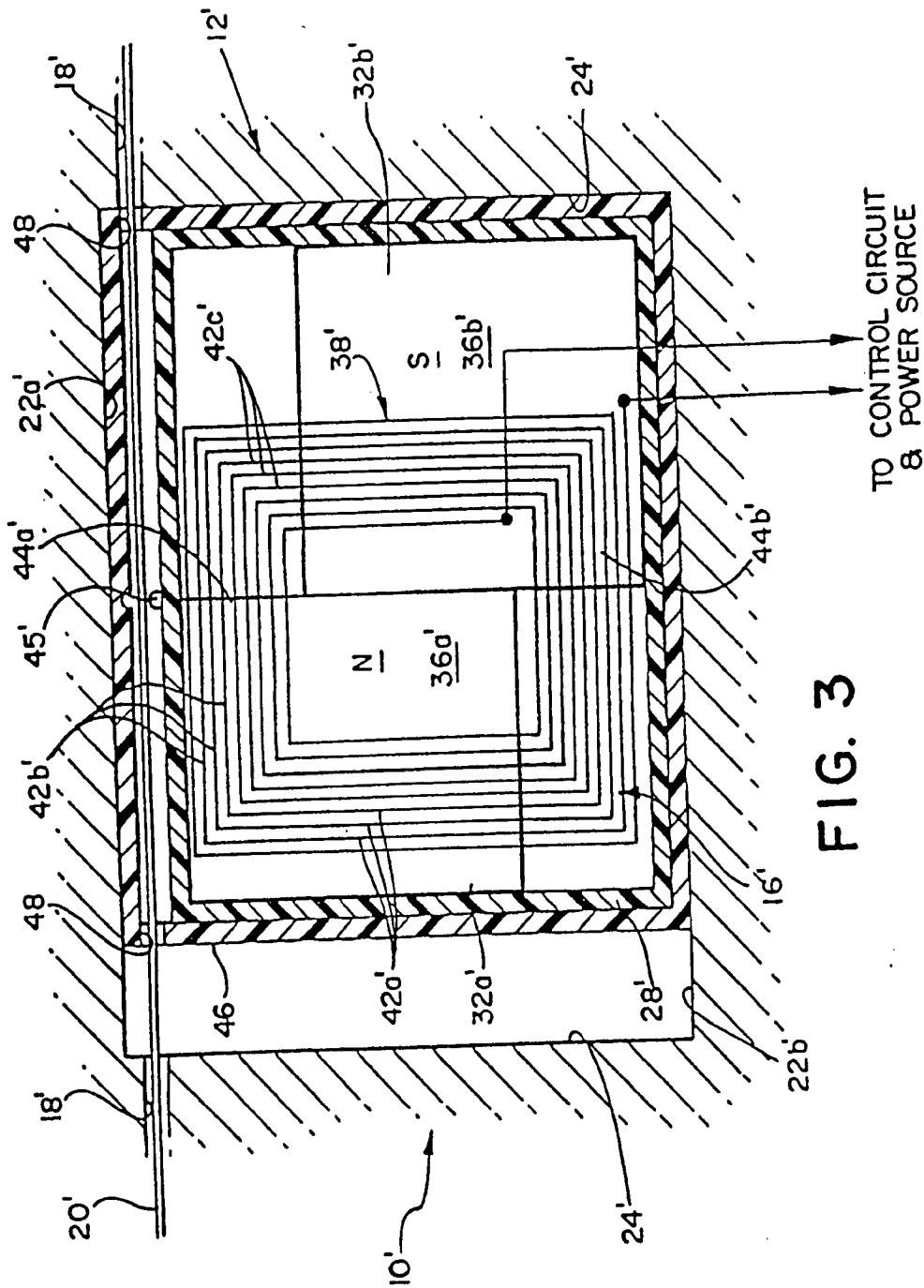


FIG. 3

47

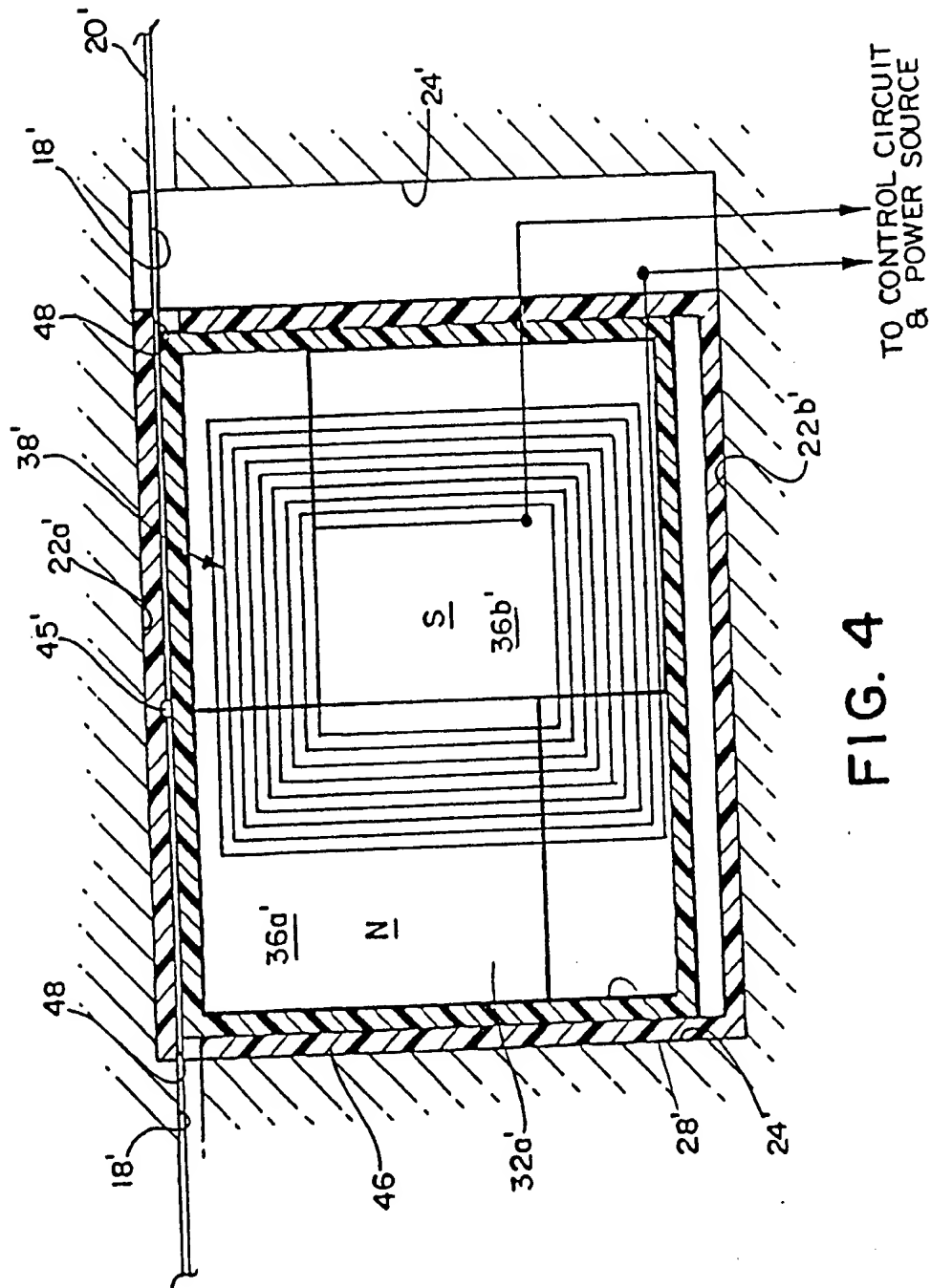
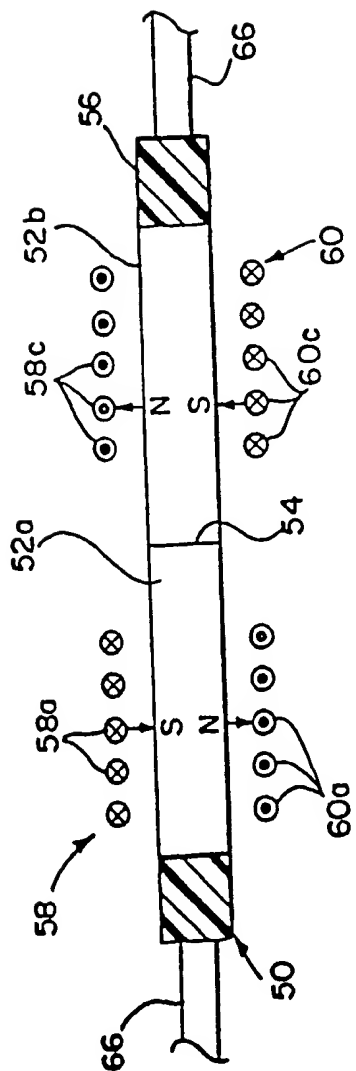
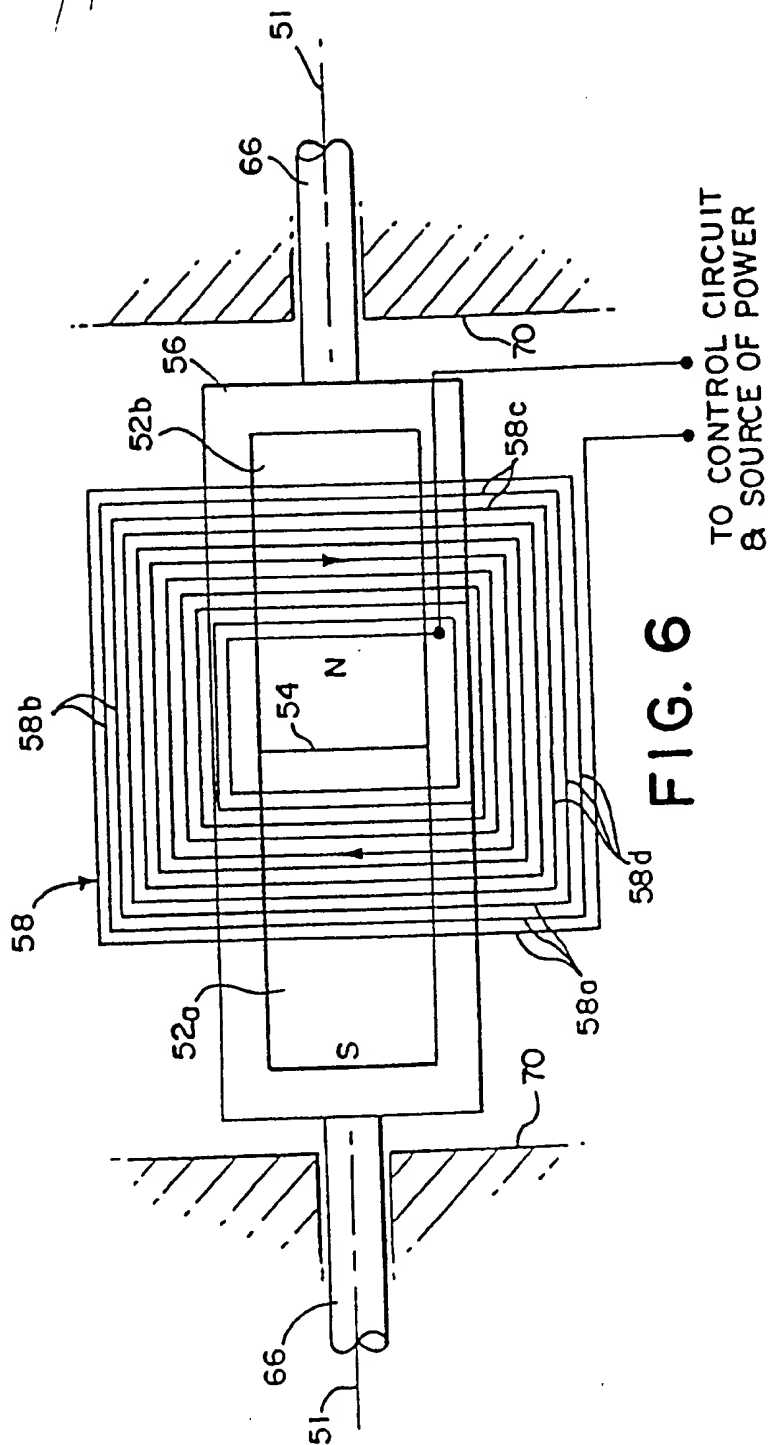


FIG. 4



5613



661

## TO CONTROL CIRCUIT & SOURCE OF POWER

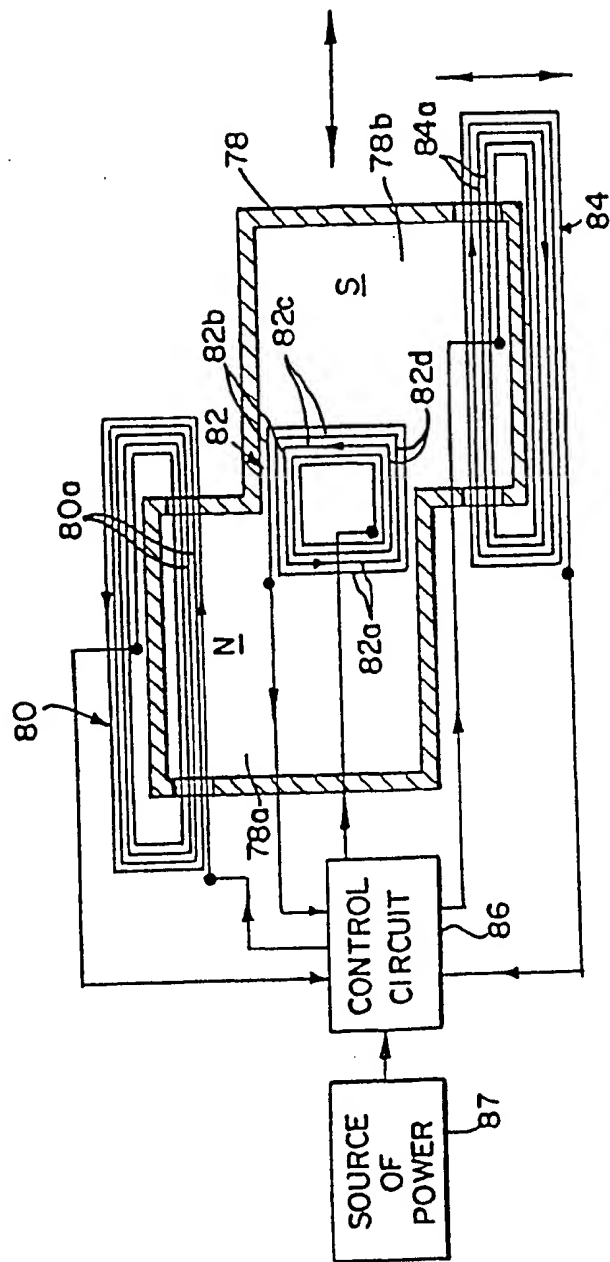
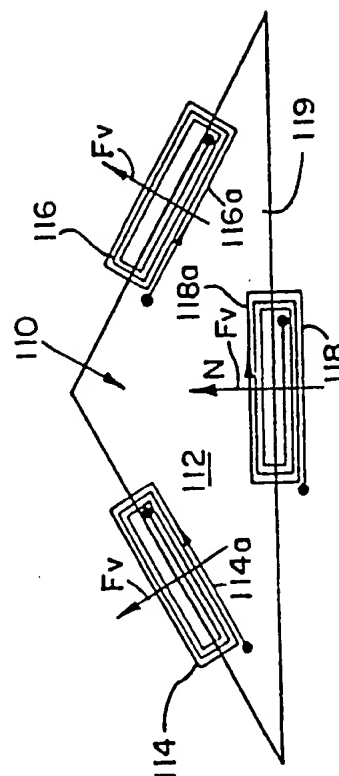
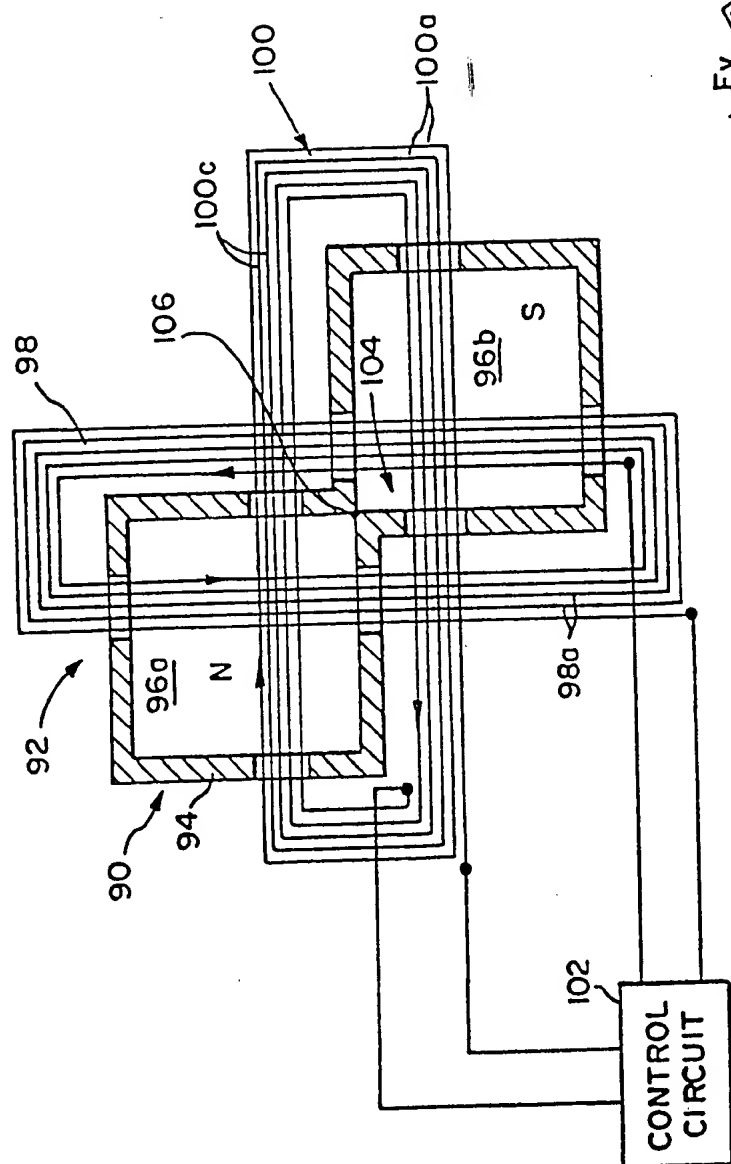


FIG. 7







DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. <sup>3</sup> )
X	DE-A-3 037 648 (JENOPTIK JENA) * Page 17, last paragraph; pages 18-23 *	1-7, 11	H 02 K 41/035 H 02 K 41/02 H 01 F 7/16
A	--- US-A-3 610 972 (MERLIN GERIN) * Column 3, lines 74-75; column 4; column 5, lines 1-28 *	1, 9	
A	--- US-A-4 314 295 (BURROUGHS CORP.)		
A	--- US-A-3 802 546 (DATA PRODUCTS CORP.)		
A	--- DE-A-2 901 287 (G. SCHMIDT)		
A	--- US-A-4 318 038 (NIPPON ELECTRIC)		
A	--- US-A-3 376 578 (B.A. SAWYER)		
A	--- DE-A-2 925 503 (TECHNOFOR LIZENZ- UND PATENTVERWERTUNGSGESELLSCHAFT) --- -/-		
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 14-07-1983	Examiner VANHULLE R.
<b>CATEGORY OF CITED DOCUMENTS</b> X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document			



DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. <sup>3</sup> )
A	PATENTS ABSTRACTS OF JAPAN, vol. 6, no. 21(E-93)(899), 6th February 1982 & JP - A - 56 139 072 (YOSHITERU TAKAHASHI) 30-10-1981  -----		
			TECHNICAL FIELDS SEARCHED (Int. Cl. <sup>3</sup> )
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 14-07-1983	Examiner VANHULLE R.
<b>CATEGORY OF CITED DOCUMENTS</b>			
X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons ----- & : member of the same patent family, corresponding document	

EPO Form 1503. 03.82